

Chapter 7

Dynamic stability analysis – I – Equations of motion and estimation of stability derivatives - 6

Lecture 27

Topics

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Example 7.1

7.17 Derivatives due to change of ' β '

These derivatives include $C_{y\beta}$, $C_{n\beta}$ and $C'_{l\beta}$

7.17.1 $C_{y\beta}$

The major contribution to this quantity is from the vertical tail. From Eq.(5.13):

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$$(Y)_{v,\text{tail}} = -\frac{1}{2} \rho V_v^2 S C_{L\alpha v} \alpha_v \quad (7.146)$$

Noting that $\alpha_v = \beta + \sigma$, $\eta_v = (\frac{1}{2} \rho V_v^2) / (\frac{1}{2} \rho V^2)$ and $C_y = Y / (\frac{1}{2} \rho V^2 S)$, Eq.(7.146) gives:

$$C_{y\beta} = -\eta_v \frac{S_v}{S} C_{L\alpha v} \left(1 + \frac{d\sigma}{d\beta}\right) \quad (7.147)$$

It may be added that $Y_\beta = \frac{QSC_{y\beta}}{m}$ (7.148)

Remark:

Reference 1.8b, chapter 7 mentions that wing and fuselage also have small contributions to $C_{y\beta}$ (see also Appendix 'C').

7.17.2 $C_{n\beta}$

From Eq.(5.21):

$$C_{n\beta} = (C_{n\beta})_w + (C_{n\beta})_{f,n,p} + V_v \eta_v C_{L\alpha v} \left(1 + \frac{d\sigma}{d\beta}\right) \quad (7.149)$$

Details regarding estimation of various terms in Eq.(7.149) are given in Sections 5.3 to 5.6.

Note that $N_\beta = \frac{QSb C_{n\beta}}{I_{zz}}$ (7.150)

7.17.3 $C'_{l\beta}$

From Eq.(6.2):

$$C'_{l\beta} = (C'_{l\beta})_w + (C'_{l\beta})_{f,n,p} + (C'_{l\beta})_{vt} \quad (7.151)$$

Details regarding estimation of different terms in Eq.(7.151) are given in section 6.5 to 6.8.

Note that $L'_\beta = \frac{QSb C'_{l\beta}}{I_{xx}}$ (7.151a)

7.18 Derivatives due to change of 'p'

These derivatives include C_{yp} , C_{np} and C'_{lp}

7.18.1 C_{yp}

Consider an airplane rolling with angular velocity 'p'. A component of the airplane which is at a distance 'z' from the x-axis would be subject to a linear

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velocity 'pz'. This would induce a sideslip angle $\beta = pz / u_0$. This sideslip angle would result in a side force. Since, the sideslip angle depends on the distance 'z' from the x-axis, the contribution to C_{yp} is mainly due to the vertical tail. When subjected to this sideslip, the vertical tail would produce a side force. The vertical location of this side force would depend on Z_v , l_v and the angle of attack of the airplane in the undisturbed flight; Z_v is the distance of the a.c. of vertical tail above of c.g.

Reference 1.8b, chapter 8 gives the following expression:

$$C_{yp} \approx (C_{yp})_{v.tail} = 2 \frac{(Z_v \cos \alpha - l_v \sin \alpha)}{b} C_{y\beta v} \quad (7.152)$$

Note that $Y_p = \frac{QS b C_{yp}}{2m u_0}$ (7.153)

Remark: C_{yp} is generally small and neglected.

7.18.2 C_{np}

The main contribution to this quantity is from the wing in the form of adverse yaw. As explained in section 5.8.1:

$$(C_n)_{adverse\ yaw} = -\frac{C_L}{8} \frac{pb}{2u_0} \quad (7.154)$$

Hence, $C_{np} = \frac{dC_n}{d(\frac{pb}{2u_0})} = -\frac{C_L}{8}$ (7.155)

Note : $N_p = \frac{QS b^2 C_{np}}{2I_{zz} u_0}$ (7.155a)

Remark:

Reference 1.8b gives a procedure which includes contributions due to vertical tail (see also Appendix 'C').

7.18.3 C'_{ip}

Main contribution C'_{ip} to this quantity is from the damping due to wing. From

Eq.(6.22):

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$$(C'_l)_{\text{damp}} = \frac{2C_{L\alpha w} \rho}{u_0 S b} \int_0^{b/2} c y^2 dy \quad (7.156)$$

Hence,

$$C'_{lp} = \frac{\partial C'_l}{\partial \left(\frac{\rho b}{2u_0} \right)} = \frac{4 C_{L\alpha w}}{S b^2} \int_0^{b/2} c y^2 dy \quad (7.157)$$

Note that: $L'_p = \frac{Q S b^2 C'_{lp}}{2 I_{xx} u_0}$ (7.158)

Remarks:

- i) The horizontal tail and vertical tail also make minor contributions to C'_{lp} (see Appendix 'C').
- ii) Reference 1.1, chapter 3 gives the following formula for C'_{lp} in terms of $C_{L\alpha w}$ and geometrical parameters of the wing.

$$C'_{lp} = - \frac{C_{L\alpha}}{12} \frac{1+3\lambda}{1+\lambda} \quad (7.158a)$$

7.19 Derivatives due to change of 'r'

These derivatives include C_{yr} , C_{nr} and C'_{lr}

7.19.1 C_{yr}

When an airplane has an angular velocity in yaw (r), then a component of the airplane at a distance ' x ' from the c.g. experiences a side ward velocity of ' rx '. This results in side slip of (rx/u_0) leading to side force and consequently C_{yr} . The major contribution to C_{yr} is due to the vertical tail. It is evident that the vertical tail has a side ward velocity of $r l_v$ and side slip angle $\Delta \beta$ of $(-r l_v / u_0)$.

This would produce a side force:

$$Y = - C_{L\alpha v} \Delta \beta Q_v S_v \quad (7.159)$$

Hence, $C_y = \frac{C_{L\alpha v} \left(\frac{l_v r}{u_0} \right) Q_v S_v}{QS} = C_{L\alpha v} \left(\frac{l_v r}{u_0} \right) \eta_v \frac{S_v}{S}$ (7.160)

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$$\text{Let, } C_{yr} = \frac{\partial C_y}{\partial \left(\frac{rb}{2u_0} \right)}, \text{ Then, } C_{yr} = 2C_{Lav} \eta_v \frac{S_v l_v}{S b} \quad (7.161)$$

Noting that, $(C_{y\beta})_{v.tail} \approx -C_{Lav} \eta_v \frac{S_v}{S}$,

$$C_{yr} = -2(C_{y\beta})_{v.tail} \frac{l_v}{b} \quad (7.162)$$

$$\text{Note that: } Y_r = \frac{Q S b C_{yr}}{2 m u_0} \quad (7.163)$$

Remark:

Y_r is generally small and in Eq.(7.88) it appears as $(u_0 - Y_r)$. Hence Y_r is often neglected.

7.19.2 C_{nr}

As mentioned above when an airplane has an angular velocity 'r' the vertical tail experiences a sideslip angle $\Delta\beta = (-l_v r / u_0)$. The side force would also produce a yawing moment given by:

$$N = C_{Lav} \Delta\beta Q_v S_v l_v = -C_{Lav} \left(\frac{l_v r}{u_0} \right) Q_v S_v l_v \quad (7.164)$$

$$\text{Or } C_n = \frac{N}{q S b} = -C_{Lav} \left(\frac{l_v r}{u_0} \right) \eta_v V_v \quad (7.165)$$

$$\text{Let, } C_{nr} = \frac{\partial C_n}{\partial \left(\frac{rb}{2u_0} \right)}, \quad (7.166)$$

$$\text{Then, } C_{nr} = -2C_{Lav} \eta_v V_v \frac{l_v}{b} \quad (7.167)$$

$$\text{Note that : } N_r = \frac{Q S b^2 C_{nr}}{2 I_{zz} u_0} \quad (7.168)$$

Remark:

When the airplane has a rate of yaw, the two wing halves experience different velocities (refer to the explanation of C'_{lr} in the next subsection) and

hence, experience different drags. This would cause a small contribution from wing to C_{nr} (see appendix 'C').

7.19.3 C'_{lr}

Consider an airplane experiencing a positive rate of yaw i.e. right wing back. Then, a section of the right wing at a distance 'y' from the x-axis would experience a velocity 'ry' or relative wind of $(u_0 - ry)$. Consequently, the dynamic pressure is lower on the right wing. For the same reason, the dynamic pressure is higher on the left wing. The lifts on the two wing halves are different, thus producing a positive rolling moment. Strip theory (as explained in subsection 6.10.2) can be used to obtain an approximate estimate of C'_l and C'_{lr} . In addition to this the side force on the vertical tail also contributes to C'_{lr} . Ref.1.1, chapter 3 gives the following approximate formula:

$$C'_{lr} = \frac{C_L}{4} - 2 \frac{l_v}{b} \frac{Z_v}{b} C_{y\beta tail} \quad (7.168a)$$

Reference 1.8b gives an improved estimates. See also Appendix 'C'.

Note that:
$$L'_r = \frac{QSb^2 C'_{lr}}{2I_{xx} u_0} \quad (7.169)$$

7.20 Lateral control derivatives:

Expressions for the derivatives $C_{n\dot{or}}$ and $C'_{l\dot{o}a}$ are given in Eq.(5.31a) and (6.27) respectively. The cross derivatives viz. $C_{n\dot{o}a}$ and $C'_{l\dot{or}}$ can be obtained from Ref. 1.1 and 1.12.

7.21 Summary of lateral stability derivatives

The expressions for the lateral stability derivatives are summarized in Table 7.7; Table 7.6 presents the list of symbols.

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$Y_{\beta} = \frac{QSC_{y\beta}}{m} \text{ (m/s}^2\text{)}$	$Y_p = \frac{QSC_{yp}}{2mu_0} \text{ (m/s)}$	$Y_r = \frac{QSC_{yr}}{2mu_0} \text{ (m/s)}$
$N_{\beta} = \frac{QSbC_{n\beta}}{I_{zz}} \text{ (s}^{-2}\text{)}$	$N_p = \frac{QSb^2C_{np}}{2I_{zz}u_0} \text{ (s}^{-1}\text{)}$	$N_r = \frac{QSb^2C_{nr}}{2I_{zz}u_0} \text{ (s}^{-1}\text{)}$
$L'_{\beta} = \frac{QSbC'_{l\beta}}{I_{xx}} \text{ (s}^{-2}\text{)}$	$L'_p = \frac{QSb^2C'_{lp}}{2I_{xx}u_0} \text{ (s}^{-1}\text{)}$	$L'_r = \frac{QSb^2C'_{lr}}{2I_{xx}u_0} \text{ (s}^{-1}\text{)}$
$Y_{\delta a} = \frac{QSC_{y\delta a}}{m} \text{ (m/s}^2\text{)}$	$Y_{\delta r} = \frac{QSC_{y\delta r}}{m} \text{ (m/s}^2\text{)}$	
$N_{\delta a} = \frac{QSbC_{n\delta a}}{I_{zz}} \text{ (s}^{-2}\text{)}$	$N_{\delta r} = \frac{QSbC_{n\delta r}}{I_{zz}} \text{ (s}^{-2}\text{)}$	
$L'_{\delta a} = \frac{QSbC'_{l\delta a}}{I_{xx}} \text{ (s}^{-2}\text{)}$	$L'_{\delta r} = \frac{QSbC'_{l\delta r}}{I_{xx}} \text{ (s}^{-2}\text{)}$	

Table 7.7 Lateral stability derivatives

Remarks:

- For expressions for $C_{y\beta}$, $C_{n\beta}$, and $C'_{l\beta}$ see Eqs. (7.147), (7.149) and (7.151) respectively.
- For expressions for C_{yp} , C_{np} and C'_{lp} . See Eqs.(7.152),(7.155) and (7.157).
- For expressions for C_{yr} , C_{nr} , C'_{lr} . See Eqs.(7.162),(7.167) and (7.168a).

Example 7.1

A general aviation airplane has the following characteristics.

$$W = 12232.6 \text{ N, } C_D = 0.035 + 0.091 C_L^2, C_{L\alpha} = 4.44 \text{ rad}^{-1}, (\bar{x}_{cg}/\bar{c}) = 0.295$$

$$\text{Wing : } S = 17.09 \text{ m}^2, b = 10.18 \text{ m, } C_{L\alpha W} = 4.17 \text{ rad}^{-1}, (x_{ac}/\bar{c} = 0.25),$$

$$\bar{c} = 1.74 \text{ m,}$$

$$\text{Fuselage : } (C_{m\alpha})_{\text{fuselage}} = 0.212 \text{ rad}^{-1}$$

$$\text{Power : } (C_{m\alpha})_{\text{power}} = 0.195 \text{ rad}^{-1}$$

$$\text{H.tail : } S_t = 4.73 \text{ m}^2, C_{L\alpha t} = 3.43 \text{ rad}^{-1}, \eta_t = 0.9,$$

$$\eta_t = 0.9, l_t = 4.63 \text{ m, } \frac{d\varepsilon}{d\alpha} = 0.438$$

Obtain the values of $C_{x\alpha}$, $C_{z\alpha}$, $C_{m\alpha}$, $C_{m\dot{\alpha}}$ and C_{mq} in a flight at a velocity of 53.64 m/s at sea level.

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Solution :

Before calculating the desired quantities, the items like C_L , C_D , $C_{m\alpha}$ and $C_{D\alpha}$ are evaluated below.

Flight is at sea level, hence, $\rho = 1.225 \text{ kg/m}^3$

$$C_L = \frac{2W}{\rho S V^2} = \frac{2 \times 12232.6}{1.225 \times 17.09 \times 53.64^2} = 0.406$$

$$C_D = 0.039 + 0.091 \times 0.406^2 = 0.050$$

From Eq.(2.65)

$$\begin{aligned} C_{m\alpha} &= C_{L_{\text{law}}} \left[\frac{x_{c\alpha}}{\bar{c}} - \frac{x_{ac}}{\bar{c}} \right] + (C_{m\alpha})_{f,p} - \bar{V} \eta C_{L_{\text{lat}}} \left(1 - \frac{d\varepsilon}{d\alpha} \right) \\ &= 4.17 [0.295 - 0.25] + 0.212 + 0.195 - \frac{4.73}{17.09} \times \frac{4.63}{1.74} \times 0.9 \times 3.43 (1 - 0.438) \\ &= 0.1877 + 0.407 - 1.2777 = -0.683 \text{ rad}^{-1} \end{aligned}$$

$$C_{D\alpha} = \frac{2C_L C_{L\alpha}}{\pi A e} = 2 \times 0.406 \times 4.44 \times 0.091 = 0.328$$

The desired quantities are evaluated below.

From Eq.(7.117)

$$C_{x\alpha} = C_L - C_{D\alpha} = 0.406 - 0.328 = 0.078$$

From Eq.(7.121)

$$C_{z\alpha} = -(C_{L\alpha} + C_D) = -(4.44 + 0.05) = -4.49$$

From Eq.(7.142a)

$$\begin{aligned} C_{m\dot{\alpha}} &= -2C_{L_{\text{lat}}} \eta V_H \frac{l_t}{\bar{c}} \frac{d\varepsilon}{d\alpha} \\ &= 2 \times 3.43 \times 0.9 \times \frac{4.73}{17.09} \times \frac{4.63}{1.74} \times \frac{4.63}{1.74} \times 0.438 = -5.3 \end{aligned}$$

From Eq.(7.133a)

$$\begin{aligned} C_{m\alpha} &= -2C_{L_{\text{lat}}} \eta V_H \frac{l_t}{\bar{c}} = C_{m\dot{\alpha}} / \left(\frac{d\varepsilon}{d\alpha} \right) \\ &= -5.3 / 0.438 = -12.1 \end{aligned}$$

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Answers:

$$C_{x\alpha} = 0.078; C_{z\alpha} = 4.49; C_{m\dot{\alpha}} = -5.3; C_{mq} = -12.1.$$